

Exercises 86 - 89

86. We have defined

$$\int_M \omega := \sum_{\alpha} \int_{\mathbb{R}^n} (\phi_{\alpha}^{-1})^* (\rho_{\alpha} \omega)$$

where $(U_{\alpha}, \phi_{\alpha})$ is an oriented atlas of M and ρ_{α} is a partition of unity subordinate to (U_{α}) .

Suppose $(V_{\alpha}, \psi_{\alpha})$ is another oriented atlas of M and χ_{α} is a partition of unity subordinate to (V_{α}) . Then

$$\sum_{\alpha} \int_{\mathbb{R}^n} (\phi_{\alpha}^{-1})^* (\rho_{\alpha} \omega) = \sum_{\alpha} \int_{\mathbb{R}^n} (\phi_{\alpha}^{-1})^* \left(\sum_{\beta} \chi_{\beta} \rho_{\alpha} \omega \right) \left[\text{since } \sum_{\beta} \chi_{\beta} = 1 \right]$$

$$= \sum_{\alpha, \beta} \int_{\mathbb{R}^n} (\phi_{\alpha}^{-1})^* (\chi_{\beta} \rho_{\alpha} \omega) \quad \left[\text{integration is linear} \right]$$

$$= \sum_{\alpha, \beta} \int_{\mathbb{R}^n} (\psi_{\beta}^{-1})^* (\chi_{\beta} \rho_{\alpha} \omega)$$

$$= \sum_{\beta} \int_{\mathbb{R}^n} (\psi_{\beta}^{-1})^* \left(\sum_{\alpha} \rho_{\alpha} \chi_{\beta} \omega \right)$$

$$= \sum_{\beta} \int_{\mathbb{R}^n} (\psi_{\beta}^{-1})^* (\chi_{\beta} \omega)$$

[since, firstly, $\text{supp } \chi_{\beta} \rho_{\alpha} \omega$ lies in $U_{\alpha} \cap V_{\beta}$, and secondly we have shown in the book that integration over a single oriented chart is independent of the coordinates used]

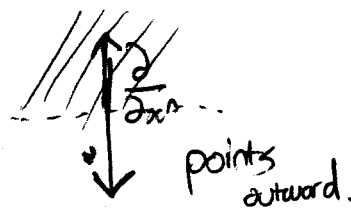
□

87. It is clear that ∂D^n , with the charts from exercise 84, in fact equals $S^{n-1} := \{(x_1, \dots, x_n) \in \mathbb{R}^n : x_1^2 + \dots + x_n^2 = 1\}$, as a smooth manifold. What we need to check is that their orientations agree. Baez + Muniain were sloppy in their definitions of the orientation on ∂M ; here is mine:

$$\left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^{n-1}} \right) \text{ is an oriented basis for } T_p \partial M$$

$$\Leftrightarrow$$

$$\left(\frac{\partial}{\partial x^n}, \frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^{n-1}} \right) \text{ is an oriented basis for } T_p M.$$

where $\frac{\partial}{\partial x^n}$ points ~~inward~~ ^{outward} : 

By this definition,

(v_1, \dots, v_n) is an oriented basis for ∂D^n if

(p, v_1, \dots, v_n) is oriented basis for D^n .

Also, the standard definition of the orientation on S^{n-1} is

(v_1, \dots, v_n) is an oriented basis for S^{n-1} if

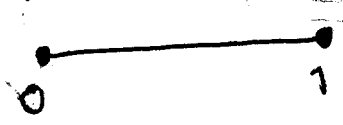
(p, v_1, \dots, v_n) is an oriented basis of \mathbb{R}^n .

Since the orientation on D^n is the orientation on the ambient \mathbb{R}^n ,

we see that the orientations on ∂D^n and S^{n-1} agree.

88. $\int_0^1 f'(x) dx = \int_{[0,1]} df = \int_{\partial[0,1]} f$ [Stokes]
 $= f(1) - f(0)$

[using my defn. of orientation on ∂M above, and the definition of integration on a zero-oriented manifold, namely sign addition].



89. In this case, Stokes' theorem would say

note mistake in question

$\int_0^\infty f'(x) dx = \int_{[0,\infty)} df$
 $= \int_{\partial[0,\infty)} f = -f(0)$

(using my convention for orientation on ∂M)

